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**Statistical inference in evolutionary dynamics. (English. English summary)**

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Each player from a unit mass population of players has two actions,  $A$  and  $B$ . Each player's payoff depends on the share of the population who plays  $A$  and an idiosyncratic component (i.e., player types). Specifically, the payoff from action  $B$  is set to zero, and the payoff from action  $A$  is given by  $u(\theta, \alpha) = \theta - f(\alpha)$ , where  $\theta$  is the agent's idiosyncratic preference and  $f(\alpha)$  is the cost of taking action  $A$  when the proportion of players playing  $A$  is  $\alpha$ .  $f(\cdot)$  is assumed to be continuous, so that for  $\alpha$  in small enough  $N \subseteq [0, 1]$ , a player is always playing a coordination game or anti-coordination game with every member of the population (uniform interaction/playing the field).

Each player's action choice follows the following individualistic dynamic. A player samples  $k$  other players from the population. From the share of these players that play  $A$ , he then generates a distribution over the share of players in the population as a whole who play  $A$ . This distribution is assumed to be monotonic in the number of sampled players who play  $A$ . This is referred to as *statistical inference*. He then plays a best response to this distribution.

Comparison is carried out between the *aggregate dynamic*, for which the state variable is the share of players who are choosing  $A$ , and a *Bayesian dynamic*, for which the state variable is the share of the players of each type who are choosing  $A$ . Theorems 1 & 2 show that these approaches effectively lead to the same outcomes.

Theorem 1 shows that the Bayesian dynamic converges if and only if the aggregate dynamic converges. The proof is an exercise in showing that convergence in the aggregate number of players choosing  $A$  leads to convergence in (probabilistic) best responses for each type of player. Theorem 2 uses monotonicity implied by the coordination/anti-coordination aspect of the problem to show convergence.

Subsequent results then study the dynamics for particular games, such as anti-coordination games (Proposition 1) and coordination games (Theorem 4).

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### [References]

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