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Stability of strict equilibria in best experienced payoff dynamics: simple formulas and applications. (English. English summary)

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Consider a population comprising a unit mass of agents. These agents are matched in groups of size $p \in \mathbb{N}$ to play a p -player symmetric normal form game with strategy set $S = \{1, \dots, n\}$ and payoff function $U: S^p \rightarrow \mathbb{R}$. The *population state* x is a vector with n elements. Element x_i denotes the fraction of agents using strategy $i \in S$.

When an agent updates his strategy he will test his current strategy against alternative strategies. Each strategy that is tested will be played in $\kappa \in \mathbb{N}$ independent *trials* against random draws of $p - 1$ other players from the population. The strategy that obtains the greatest total payoff across all trials is then selected by the agent. If there is a tie, then some tie-breaking rule is applied.

Let each agent in the population update at Poisson rate 1. Let $w_i(x)$ denote the probability that an agent chosen uniformly at random from the population will select strategy i when he follows the above procedure. This gives the *best experienced payoff dynamics* $\dot{x}_i = w_i(x) - x_i$, the expected motion of the population from each state.

Let $s \in S$ be a strategy such that (s, \dots, s) is a strict symmetric Nash equilibrium of the game. Let e_s be the state at which every agent in the population plays s . Let v_{ij}^s be the total payoff to $i \in S$ when it is matched exclusively to players playing s in $\kappa - 1$ trials, and in the remaining trial matches with $(p - 1)$ players playing s and a single player playing $j \in S$. These are the important payoffs to consider when almost everyone in the population plays strategy s , as the probability of matching with two or more players who do not play s is an order of magnitude lower than the probability of matching with one player who does not play s .

Let S_2 be the set of strategies that obtain the second-best payoff v_{ts}^s when playing against s players. That is, $S_2 = \arg \max_{i \neq s} v_{is}^s$.

Strategy $j \in S$ is *s-stabilizing* in $J \subseteq S \setminus \{s\}$ if

1. $v_{ij}^s < v_{ss}^s$ for all $i \in J$, and
2. if $S_2 \cap J \neq \emptyset$, then $v_{sj}^s > v_{ts}^s$.

Intuitively, in a neighborhood of e_s , if j is *s-stabilizing* in J , then j does not help any other strategy in J (including itself) to destabilize e_s . If a revising agent samples one player using strategy $j \neq s$, then condition (1) ensures that if the j -player is met when testing strategy i , then i does worse than s , so that s is selected over i . Similarly, condition (2) ensures that if the j -player is met when testing strategy s , then no strategy in J is selected.

The above suggests a procedure that gives a sufficient condition for stability of e_s . If a strategy i is *s-stabilizing* in $S \setminus \{s\}$, then it does not help any other strategy to destabilize e_s . We remove i from the strategy set and consider the reduced problem with strategy set $S \setminus \{i\}$. If, continuing in this manner, it is possible to remove all strategies in $S \setminus \{s\}$, then it must be that s is stable under the best experienced payoff dynamics. This is Proposition 4.2, one of the main results of the paper.

Another main contribution, Proposition 4.1, establishes a result in the other direction, using a weaker version of *s-stabilizing* strategies, *potentially s-stabilizing* strategies. If some strategy survives the iterated deletion of such strategies, it is shown that e_s is unstable.

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